Form 1449 (Modified)

Information Disclosure
Statement By Applicant

(Use Several Sheets if Necessary)

Atty Docket No.
IMM1P050A
Applicant

Applicant:

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Martin et al.
Filing Date: 5/15/00

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II.S. Patent Documents

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Examiner	T .					Sub-	Filing	
Initial	No.	Patent No.	Date	Patentee	Class	class	Date	
Q8	A	3,490,059	1/13/70	Paulsen et al.	73	133	6/6/66	
RD	В	3,903,614	9/9/75	Diamond et al.	35	12S	3/27/70	
03	C	3,919,691	11/11/75	Noll	340	172.5	5/26/71	
00	D	4,148,014	4/3/79	Burson	340	709	4/6/77	
QB.	E	4,227,319	10/14/80	Guy et al.	35	12S	3/5/79	
OBO	F	4,398,889	8/16/83	Lam et al.	434	45	6/8/81	
88	G	4,477,043	10/16/84	Repperger	244	223	10/16/84	
18	H	4,560,983	12/24/85	Williams	340	825	9/17/82	
A DO	T	4,603,284	7/29/86	Perzley	318	568	6/5/84	
20	17	4,632,341	12/30/86	Repperger et al.	244	230	2/6/85	
.018	K	4,677,355	6/30/87	Baumann	318	160	5/27/86	

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Examiner	⊤		Publication	Country or		Sub-	Tran	slation
Initial	No.	No.	Date	Patent Office	Class	class	Yes	No
OB	L	0 085 518	8/10/83	EPO		<u> </u>	X	
Ro	M	0 111 992	6/27/84	EPO		_	X	<u> </u>
80	N	0470257A1	12.02.92	EPO		<u> </u>	X	<u></u>
80	0	0655301A1	31.05.95	EPO			X	<u> </u>
03	P	WO9520788	03.08.95	PCT		-	X	

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2.6	,	Louis Rosenberg, "A Force Feedback Programming Primer," Immersion Corporation, 1997, pp. 1-176.					
do	T	Patrick Fischer et al., "Specification and Design of Input Devices for Teleoperation," IEEE CH2876-1, 1990, pp. 540-545.					
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Information Disclosure Statement By Applicant	Applicant: Martin et al. Filing Date: 5/15/00	Group 2673
(Tice Several Sheets if Necessary)	`	

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20	A	4,734,685	3/29/88	Watanabe	340	710	7/18/84
20	В	4,775,289	10/4/88	Kazerooni	414	735	9/25/87
RO	C.	4,795,296	1/3/89	Jau	414	5	11/17/86
. 10	D	4,800,721	1/31/89	Cemenska et al.	60	393	2/13/87
B	E	4,811,608	3/14/89	Hilton ·	73	862.04	11/6/86
00	F	4,815,006	3/89	Andersson et al.	395	89	·
Q.S	G	4,819,195	4/4/89	Bell et al.	364	571.05	1/20/87
RB	H	4,823,634	4/25/89	Culver.	74	471 XY	11/3/87
100	I	4,840,634	6/89	Muller et al.	623	24	
DS	J	4,868,549	9/19/89	Affinito et al.	340	710	5/18/87
Do	K	4,914,976	4/10/90	Wyllie ·	· 74 ·	523	4/13/88

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80	L	0875819	Nov 11 98	EPO	-		X	<u> </u>
00	M	WO9532459	11/30/95	PCT			X	
88	N	0470257A1	Feb 12 92	EPO			X	<u> </u>
28	0	0655301A1	May 31 95	EPO			X	
26	P	0626634A2	Nov 30 94	EPO			X	

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26	S	Antal K. Bejczy et al., "The Phantom Robot: Predictive Displays for Feleoperation with Time Display," IEEE CH2876-1, 1990, pp. 546-550.			
DO	Т	Louis B. Rosenberg, "The Use of Virtual Fixtures as Perceptual Overlays to Enhance Operator Performance in Remote Environments" Crew Systems Directorate Biodynamics and Biocommunications Div., Wright—Patterson AFB OH 45433-7901, 1992, pp. 1-42.			
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				364	146	9/30/88
				33	502	2/17/89
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				74	471 XY	1/22/90
				434	45	1/12/89
				244	228	8/14/89
<u> </u>					6A	
					448 B	6/8/90
J V				414	5	
	No. A B C D E F G H I J	A 4,935,728 B 4,961,038 C 4,962,448 D 4,982,504 E 4,983,901 F 5,007,300 G 5,044,956 H 5,076,517 I 5,107,080 J 5,116,051	No. Patent No. Date A 4,935,728 6/19/90 B 4,961,038 10/2/90 C 4,962,448 10/9/90 D 4,982,504 1/8/91 E 4,983,901 1/8/91 F 5,007,300 4/16/91 G 5,044,956 9/3/91 H 5,076,517 12/31/91 I 5,107,080 4/92 J 5,116,051 5/26/92	No. Patent No. Date Patentee A 4,935,728 6/19/90 Kley B 4,961,038 10/2/90 MacMinn C 4,962,448 10/9/90 DeMaio et al. D 4,982,504 1/8/91 Soderberg et al. E 4,983,901 1/8/91 Lehmer F 5,007,300 4/16/91 Siva G 5,044,956 9/3/91 Behensky et al. H 5,076,517 12/31/91 Ferranti et al. I 5,107,080 4/92 Rosen J 5,116,051 5/26/92 Moncrief et al.	No. Patent No. Date Patentee Class A 4,935,728 6/19/90 Kley 340 B 4,961,038 10/2/90 MacMinn 318 C 4,962,448 10/9/90 DeMaio et al. 364 D 4,982,504 1/8/91 Soderberg et al. 33 E 4,983,901 1/8/91 Lehmer 318 F 5,007,300 4/16/91 Siva 74 G 5,044,956 9/3/91 Behensky et al. 434 H 5,076,517 12/31/91 Ferranti et al. 244 I 5,107,080 4/92 Rosen 200 J 5,116,051 5/26/92 Moncrief et al. 273	No. Patent No. Date Patentee Class Class A 4,935,728 6/19/90 Kley 340 709 B 4,961,038 10/2/90 MacMinn 318 696 C 4,962,448 10/9/90 DeMaio et al. 364 146 D 4,982,504 1/8/91 Soderberg et al. 33 502 E 4,983,901 1/8/91 Lehmer 318 685 F 5,007,300 4/16/91 Siva 74 471 XY G 5,044,956 9/3/91 Behensky et al. 434 45 H 5,076,517 12/31/91 Ferranti et al. 244 228 I 5,107,080 4/92 Rosen 200 6A J 5,116,051 5/26/92 Moncrief et al. 273 448 B

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do	T	Bernard D. Adelstein et al., "A High Performance Two Degree-of-freedom Kinesthetic Interface", MIT, Cambridge, MA, 1992, pp. 108-112.				
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Q0	A	5,125,261	6/30/92	Powley	73	1J	5/28/91
at at	B .	5,142,931	9/1/92	Menahem	74	471 XY	2/14/91
10	$\frac{1}{C}$	5,143,505	9/1/92	Burdea et al.	414	5	2/26/91
43	$\frac{1}{D}$	5,146,566	9/8/92	Hollis Jr. et al.	395	275	5/29/91
. 00	E	5,148,377	9/15/92	McDonald	364	560	6/12/89
RO	F	5,156,363	10/20/92	Cizewski et al.	244	223	2/28/91
23	G	5,182,557.	1/93	Lang	341	20	
D	H	5,184,319	2/2/93	Kramer	364	806	2/2/90
28	+ + + + + + + + + + + + + + + + + + + +	5,185,561	2/9/93	Good et al.	318	432	7/23/91
23	+-	5,193,963	3/16/93	McAffee et al.	414	5	10/31/90
(D)	K	5,195,179	3/16/93	Tokunaga	395	161	5/21/90
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OB		Tetsuo Kotoku, "A Predictive Display with Force Feedback and its Application to Remote Manipulation System with Transmission Time Delay", IEEE 0-7803-0737-2, 1992, pp. 239-246.
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OS .	A	5,204,600	4/20/93	Kahkoska	318	602	2/6/91
QD	B	5,206,930	4/27/93	Ishikawa et al.	395	95	2/7/92
000	$\frac{D}{C}$	5,209,131	5/11/93	Baxter	73 .	865.8	10/12/90
QD	$\frac{1}{D}$	5,220,260	6/15/93	Schuler	318	561	10/24/91
	E	5,223,776	6/93	Radke et al.	318	568.1	
ID ID	F	5,228,356	7/20/93	Chuang	74	471	11/25/91
IB.	G	5,230,623	7/27/93	Guthrie et al.	433	72	12/10/91
00	H	5,235,868	8/17/93	Culver	74	471 XY	10/2/91
QB	+++	5,239,246	8/24/93	Kim	318	568	7/8/92
88	++	5,254,919	10/19/93	Bridges et al.	318	560	3/22/91
08	+ K	5,264,768	11/23/93	Gregory et al.	318	561	10/6/92
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28	S	Pietro Buttolo et al., "Pen-based Force Display for Precision Manipulation in Virtual Environments", IEEE 0-8186-7084-3, 1995, pp. 217-224.
88	T	Brain Schmult et al., "Application Areas for a Force-feedback Joystick", DSC-Vol. 49, Advances in Robotics, Mechatronics, and Haptic Interfaces, 1993, pp. 47-54.
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100	A A	5,286,203	2/15/94	Fuller et al.	434	45	10/7/92
90	B	5,296,846	3/22/94	Ledley	345	161	10/5/92
20	$\frac{1}{c}$	5,296,871	3/22/94	Paley	345	163 ·	7/27/92
28	D	5,327,790	7/12/94	Levin et al.	. 73	862.325	6/19/92
· 00	E	5,341,459	8/23/94	Backes	395 ·	95	8/9/91
08	F	5,355,148	10/11/94	Anderson	345	166	1/14/93
W	G	5,374,942	12/20/94	Gilligan et al.	345	157	8/12/93
as s	TH.	5,389,865	2/14/95	Jacobus et al.	318	568.11	12/2/92
DE DE	T	5,396,266	3/7/95	Brimhall	345	161	6/8/93
88	+ 🕂	5,398,044	3/14/95	Hill .	345	145	12/7/93
NG NG	K	5,402,582	4/4/95	Raab	33	503	2/23/93

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Group 2673

(Use Several Sheets if Necessary)

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00	B	5,414,337	5/9/95	Schuler	318	561	6/11/93
00	C	5,473,235	12/5/95	Lance et al.	318	561	.12/21/93
W		5,477,237	12/19/95	Parks	345	156	7/14/94
28	E	5,482,051	1/96	Reddy et al.	128	733	
D	F	5,512,919	4/30/96	Araki	345	156	03/30/93
W.	G	5,513,100	4/30/96	Parker et al.	364	167.01	06/10/93
207	H	5,551,701	9/3/96	Bouton et al.	463	36	1/5/94
D	I	5,570,111	10/29/96	Barrett et al.	345	157	10/3/94
87	1	5,576,727	11/19/96	Rosenberg et al.	345	179	06/05/95
100	K	5,587,937	12/24/96	Massie et al.	364	578	4/25/95

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Form 1449 (Modified) Information Disclosure Statement By Applicant	Atty Docket No. IMM1P050A Applicant: Martin et al. Filing Date: 5/15/00	Serial No.: 09/571,397 Group 2673
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DB	B	5,589,854	12/96	Tsai	345	161	
DD .	1. C	5,591,082	1/7/97	Jensen et al.	463	38	1/5/95
NO TO	D	5,611,731	3/18/97	Bouton et al.	463	37	9/8/95
No.	E	5,623,582	4/97	Rosenberg	395	99 .	
De	$+\frac{2}{F}$	5,629,594	5/13/97	Jacobus et al.	318	568.11	10/16/95
B	G	5,642,469	06/24/97	Hannaford et al.	395	99	.11/03/94
QD.	H	5,643,087	7/97	Marcus et al.	463	38	
Jo.	 	5,656,901	8/12/97	Kurita	318	436	4/21/95
2	1	5,666,138	09/09/97	Culver	345	161	11/22/94
100	K	5,680,141	10/97	Didomenico et al.	342	372	

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DO	T	Hannaford, B. et al., "Performance Evaluation of a Six-Axis Generalized Force-Reflecting Teleoperator," IEEE Transactions on Systems, Man, and Cybernetics, Vol. 21, No. 3, 1991, pp. 620-623, 631-633.
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88	A		1/20/98	Chen et al.	128	782	8/1/96
DB	B	5,709,219	2/3/98	Yamanaka et al.	345	157	12/5/95
DP.	C	5,714,978			345	161	6/9/95
OB	D	5,721,566	2/24/98	Rosenberg et al.	345	161	1
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Group 2673

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